

## ECL 4340

### POWER SYSTEMS

#### LECTURE 1

INTRODUCTION

Professor Kwang Y. Lee

Department of Electrical and Computer Engineering

Baylor University

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## ABOUT PROF. KWANG LEE

- **Professional**
  - BSEE from Seoul National University, MSEE from North Dakota State, Ph.D. from Michigan State
  - ROTC & Army Signal Corps for 2 years
  - Electric Industry (Han Young) for 1 year
  - Faculty at MSU, OSU, UH, Penn State doing teaching and research in electric power systems
  - Have been at Baylor since 2007 as ECE Chair
  - Doing research in power systems, power plants, fuel cell, intelligent systems
  - Teaching power systems, linear systems, optimal control, intelligent control

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## ABOUT PROF. KWANG LEE

- **Personal**
  - Married to Sangwol
  - Have two sons & 6 grandchildren
    - Jonathan age 26
    - Owen age 23
    - Franziska age 19
    - Esme age 17
    - Jesse age 14
    - Teddy age 11
  - Live near campus on Hackberry Ave
  - Member of Fellowship Bible Church on Speegleville Road
  - Attend Bible Study Fellowship on Monday evenings



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## ANNOUNCEMENT

- Please read Chapters 1 and 2
- HW 1; Project 1 – due Wednesday 8/31, in Canvas
  - in-class quiz, randomly administered
  - For Project, you need to use the PowerWorld Software. You can download the software and cases at the link below; get version 19 (August 6, 2018)  
<http://www.powerworld.com/gloveroberbyesarma.asp>

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## SIMPLE POWER SYSTEM

- Every power system has three major components
  - ❖ generation: source of power, ideally with a specified voltage and frequency
  - ❖ load: consumes power; ideally with a constant resistive value
  - ❖ transmission system: transmits power; ideally as a perfect conductor

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## COMPLICATIONS

- ❖ No ideal voltage sources exist
- ❖ Loads are seldom constant
- ❖ Transmission system has resistance, inductance, capacitance and flow limitations
- ❖ Simple system has no redundancy so power system will not work if any component fails

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## NOTATION - POWER

- Power: Instantaneous consumption of energy
- Power Units
  - ❖ Watts = voltage x current for dc (W)
  - ❖ kW =  $1 \times 10^3$  Watt
  - ❖ MW =  $1 \times 10^6$  Watt
  - ❖ GW =  $1 \times 10^9$  Watt
- Installed U.S. generation capacity is about 1000 GW ( about 3 kW per person)
- Maximum load of Greater Waco about 2 GW

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## NOTATION - ENERGY

- Energy: Integration of power over time; energy is what people really want from a power system
- Energy Units
  - ❖ Joule = 1 Watt-second (J)
  - ❖ kWh = Kilowatthour ( $3.6 \times 10^6$  J)
  - ❖ Btu = 1055 J; 1 MBtu=0.292 MWh
  - ❖ One gallon of gas has about 0.125 MBtu (36.5 kWh);
- U.S. electric energy consumption is about 3600 billion kWh (about 13,333 kWh per person, which means on average we each use 1.5 kW of power continuously)

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## POWER SYSTEM EXAMPLES

- Electric utility: can range from quite small, such as an island, to one covering half the continent
  - ❖ there are four major interconnected ac power systems in North American, each operating at 60 Hz ac; 50 Hz is used in some other countries.
- Airplanes and Spaceships: reduction in weight is primary consideration; frequency is 400 Hz.
- Ships and submarines
- Automobiles: dc with 12 volts standard
- Battery operated portable systems

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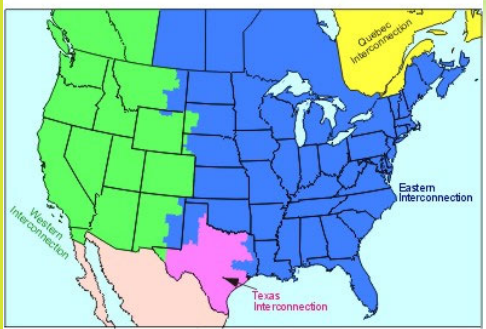
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## NORTH AMERICA INTERCONNECTIONS



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## REVIEW OF PHASORS

Goal of phasor analysis is to simplify the analysis of constant frequency ac systems

$$v(t) = V_{\max} \cos(\omega t + \theta_v)$$

$$i(t) = I_{\max} \cos(\omega t + \theta_i)$$

Root Mean Square (RMS) voltage of sinusoid

$$\sqrt{\frac{1}{T} \int_0^T v(t)^2 dt} = \frac{V_{\max}}{\sqrt{2}}$$

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## PHASOR REPRESENTATION

Euler's Identity:  $e^{j\theta} = \cos \theta + j \sin \theta$

Phasor notation is developed by rewriting using Euler's identity

$$v(t) = \sqrt{2}|V| \cos(\omega t + \theta_v)$$

$$v(t) = \sqrt{2}|V| \operatorname{Re} \left[ e^{j(\omega t + \theta_v)} \right]$$

(Note:  $|V|$  is the RMS voltage)

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## PHASOR REPRESENTATION

The RMS, cosine-referenced voltage phasor is:

$$V = |V|e^{j\theta_V} = |V|\angle\theta_V$$

$$v(t) = \text{Re}\sqrt{2} V e^{j\omega t} e^{j\theta_V}$$

$$V = |V|\cos\theta_V + j|V|\sin\theta_V$$

$$I = |I|\cos\theta_I + j|I|\sin\theta_I$$

(Note: Some texts use “boldface” type for complex numbers, or “bars on the top”)

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## ADVANTAGES OF PHASOR ANALYSIS

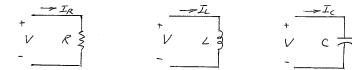
Device	Time Analysis	Phasor
Resistor	$v(t) = Ri(t)$	$V = RI$
Inductor	$v(t) = L \frac{di(t)}{dt}$	$V = j\omega LI$
Capacitor	$\frac{1}{C} \int_0^t i(t) dt + v(0)$	$V = \frac{1}{j\omega C} I$
$Z = \text{Impedance} = R + jX =  Z \angle\phi$		
$R = \text{Resistance}$		
$X = \text{Reactance}$		
$ Z  = \sqrt{R^2 + X^2} \quad \phi = \arctan\left(\frac{X}{R}\right)$		

(Note:  $Z$  is a complex number but not a phasor)

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## BASIC PRINCIPLES

Impedances: passive elements



Impedances of resistance, inductance, and capacitance are:

$$Z_R = R, \quad Z_L = j\omega L = jX_L, \quad Z_C = \frac{1}{j\omega C} = -jX_C$$

Currents are, by Ohm's law:  $I = \frac{V}{Z}$

$$I_R = \frac{V}{Z_R} = \frac{V}{R}, \quad I_L = \frac{V}{jX_L} = -j \frac{V}{X_L}, \quad I_C = \frac{V}{-jX_C} = j \frac{V}{X_C}$$



Current is: in-phase, lagging by  $90^\circ$ , leading by  $90^\circ$ .

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## BASIC PRINCIPLES

In general, we have a combination of  $R, L, C$

$$Z = |Z| \angle \theta = R + jX$$

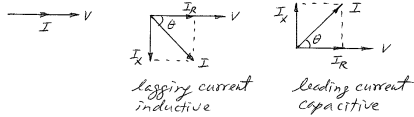
$\theta > 0, X > 0$  : inductive reactance

$\theta < 0, X < 0$  : capacitive reactance

$$I = \frac{V}{Z} = \frac{V}{|Z|} \angle -\theta$$

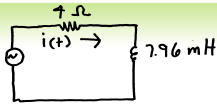
$\theta > 0$ , inductive : lagging current

$\theta < 0$ , capacitive : leading current



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## RL CIRCUIT EXAMPLE



$$V(t) = \sqrt{2} 100 \cos(\omega t + 30^\circ)$$

$$f = 60 \text{ Hz}$$

$$R = 4 \Omega \quad X = \omega L = 3$$

$$|Z| = \sqrt{4^2 + 3^2} = 5 \quad \phi = 36.9^\circ$$

$$I = \frac{V}{Z} = \frac{100 \angle 30^\circ}{5 \angle 36.9^\circ}$$

$$= 20 \angle -6.9^\circ \text{ Amps}$$

$$i(t) = 20\sqrt{2} \cos(\omega t - 6.9^\circ)$$

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## COMPLEX POWER

### Power

$$p(t) = v(t) \cdot i(t)$$

$$v(t) = V_{\max} \cos(\omega t + \theta_V)$$

$$i(t) = I_{\max} \cos(\omega t + \theta_I)$$

$$\cos \alpha \cos \beta = \frac{1}{2} [\cos(\alpha - \beta) + \cos(\alpha + \beta)]$$

$$p(t) = \frac{1}{2} V_{\max} I_{\max} [\cos(\theta_V - \theta_I) + \cos(2\omega t + \theta_V + \theta_I)]$$

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## COMPLEX POWER

Average Power

$$p(t) = \frac{1}{2} V_{\max} I_{\max} [\cos(\theta_V - \theta_I) + \cos(2\omega t + \theta_V + \theta_I)]$$

$$P_{\text{avg}} = \frac{1}{T} \int_0^T p(t) dt$$

$$= \frac{1}{2} V_{\max} I_{\max} \cos(\theta_V - \theta_I)$$

$$= |V||I| \cos(\theta_V - \theta_I)$$

$$\text{Power Factor Angle} = \phi = \theta_V - \theta_I$$

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## COMPLEX POWER

$$S = |V||I|[\cos(\theta_V - \theta_I) + j \sin(\theta_V - \theta_I)]$$

$$= P + jQ$$

$$= V I^*$$

(Note: S is a complex number but not a phasor)

P = Real Power (W, kW, MW)

Q = Reactive Power (var, kvar, Mvar)

S = Complex power (VA, kVA, MVA)

Power Factor (pf) =  $\cos \phi$

If current leads voltage then pf is leading

If current lags voltage then pf is lagging

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## COMPLEX POWER

Relationships between real, reactive and complex power

$$P = |S| \cos \phi$$

$$Q = |S| \sin \phi = \pm |S| \sqrt{1 - pf^2}$$

**Ex:** A load draws 100 kW with a **leading** pf of 0.85. What are  $\phi$  (power factor angle), Q and  $|S|$ ?

$$\phi = -\cos^{-1} 0.85 = -31.8^\circ$$

$$|S| = \frac{100 \text{ kW}}{0.85} = 117.6 \text{ kVA}$$

$$Q = 117.6 \sin(-31.8^\circ) = -62.0 \text{ kVar}$$

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## COMPLEX POWER

Impedance & Power:

$$\vec{z} = R + jX = |\vec{z}| \angle \theta$$

$$V = I \vec{z}, \quad V = |V| \angle 0^\circ, \text{ reference } \delta = 0^\circ$$

$$\Rightarrow I = \frac{V}{\vec{z}} = \frac{|V| \angle 0^\circ}{|\vec{z}| \angle \theta} = \frac{V}{|\vec{z}|} \angle -\theta$$

$$P = |V| |I| \cos \theta = (|I| |\vec{z}|) |I| \cos \theta$$

$$= |I|^2 |\vec{z}| \cos \theta = |I|^2 R$$

$$Q = |V| |I| \sin \theta = (|I| |\vec{z}|) |I| \sin \theta$$

$$= |I|^2 |\vec{z}| \sin \theta = |I|^2 X$$

$$P = I^2 R \quad Q = I^2 X$$

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## COMPLEX POWER

Note:  $\sqrt{P^2 + Q^2} = \sqrt{(|V||I|)^2 \cos^2 \theta + (|V||I|)^2 \sin^2 \theta}$

$$= |V| |I| \triangleq |S|, \text{ "apparent power"}$$

Power factor & Power factor angle:

$$\frac{Q}{P} = \frac{|V||I| \sin \theta}{|V||I| \cos \theta} = \tan \theta$$

$$pf = \cos \theta = \frac{P}{\sqrt{P^2 + Q^2}} = \frac{P}{|S|} = \frac{P}{|V||I|}$$

Note: the impedance angle  $\theta$  is preserved in the power triangle!

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## COMPLEX POWER

Complex Power: Let  $V = |V| \angle \delta$   
 $I = |I| \angle \beta$ 

Define

$$S = V I^* = (|V| \angle \delta) (|I| \angle -\beta) = |V| |I| \angle \delta - \beta = |S| \angle \delta - \beta$$

$$= \underbrace{|V| |I| \cos(\delta - \beta)}_P + j \underbrace{|V| |I| \sin(\delta - \beta)}_Q$$

$$|S| = |V| |I| : \text{apparent power [VA]}$$

$$\theta = \delta - \beta : \text{power factor angle}$$

$$\delta > \beta: \theta > 0, Q > 0, I \text{ lagging, inductive load}$$

$$\delta < \beta: \theta < 0, Q < 0, I \text{ leading, capacitive load}$$

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## COMPLEX POWER

Impedance & Complex power:

$$\begin{aligned}
 S &= VI^* = (I \angle \theta)(I^*) = |I|^2 \angle \theta \\
 &= |I|^2 |Z| \angle \theta = |S| \angle \theta \\
 &= |I|^2 (R + jX) = \underbrace{|I|^2 R}_P + j \underbrace{|I|^2 X}_Q
 \end{aligned}$$

Alternatively,

$$\begin{aligned}
 S &= VI^* = V \left( \frac{1}{Y} \right)^* = \frac{VI^*}{Y^*} = |V|^2 Y^* \\
 &= \frac{|V|^2}{|Y|} \angle \theta = |S| \angle \theta \\
 &= |V|^2 |Y| \angle \theta = |V|^2 (\underbrace{G}_P + j \underbrace{B}_Q) \\
 &= \underbrace{|V|^2 G}_P + j \underbrace{|V|^2 B}_Q
 \end{aligned}$$

Here,  $Y = \frac{1}{Z}$ , admittance  
 $= G - jB$

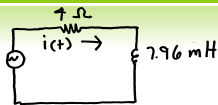
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## CONSERVATION OF POWER

- At every node (bus) in the system
  - Sum of real power into node must equal zero
  - Sum of reactive power into node must equal zero
- This is a direct consequence of Kirchhoff's current law, which states that the total current into each node must equal zero.
  - Conservation of power follows since  $S = VI^*$

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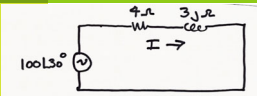
## RL CIRCUIT EXAMPLE



$$\begin{aligned}
 V(t) &= \sqrt{2} 100 \cos(\omega t + 30^\circ) \\
 f &= 60 \text{ Hz} \\
 R &= 4 \Omega \quad X = \omega L = 3 \\
 |Z| &= \sqrt{4^2 + 3^2} = 5 \quad \phi = 36.9^\circ \\
 I &= \frac{V}{Z} = \frac{100 \angle 30^\circ}{5 \angle 36.9^\circ} \\
 &= 20 \angle -6.9^\circ \text{ Amps} \\
 i(t) &= 20\sqrt{2} \cos(\omega t - 6.9^\circ)
 \end{aligned}$$

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## CONSERVATION OF POWER



Earlier we found  
 $I = 20\angle -6.9^\circ$  amps

Find complex power, real power and reactive power of the source and line components.

$$S = VI^* = 100\angle 30^\circ \times 20\angle -6.9^\circ = 2000\angle 36.9^\circ \text{ VA}$$

$$\phi = 36.9^\circ \quad \text{pf} = 0.8 \text{ lagging}$$

$$S_R = V_R I^* = 4 \times 20\angle -6.9^\circ \times 20\angle -6.9^\circ$$

$$P_R = 1600 \text{ W} = |I|^2 R \quad (Q_R = 0)$$

$$S_L = V_L I^* = 3j \times 20\angle -6.9^\circ \times 20\angle -6.9^\circ$$

$$Q_L = 1200 \text{ var} = |I|^2 X \quad (P_L = 0)$$

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## POWER CONSUMPTION IN DEVICES

Resistors only consume real power

$$P_{\text{Resistor}} = |I_{\text{Resistor}}|^2 R$$

Inductors only consume reactive power

$$Q_{\text{Inductor}} = |I_{\text{Inductor}}|^2 X_L$$

Capacitors only generate reactive power

$$Q_{\text{Capacitor}} = -|I_{\text{Capacitor}}|^2 X_C \quad X_C = \frac{1}{\omega C}$$

$$Q_{\text{Capacitor}} = -\frac{|V_{\text{Capacitor}}|^2}{X_C} \quad (\text{Note-some define } X_C \text{ negative})$$

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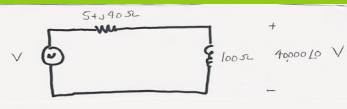
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## EXAMPLE



First solve basic circuit:

$$I = \frac{40000\angle 0^\circ \text{ V}}{100\angle 0^\circ \Omega} = 400\angle 0^\circ \text{ Amps}$$

$$V = 40000\angle 0^\circ + (5 + j40) 400\angle 0^\circ$$

$$= 42000 + j16000 = 44.9\angle 20.8^\circ \text{ kV}$$

$$S = VI^* = 44.9\text{k}\angle 20.8^\circ \times 400\angle 0^\circ$$

$$= 17.98\angle 20.8^\circ \text{ MVA} = 16.8 + j6.4 \text{ MVA}$$

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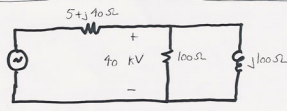
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## EXAMPLE



Now add additional reactive power load & resolve:

$$Z_{Load} = 70.7 \angle 45^\circ \quad pf = 0.7 \text{ lagging}$$

$$I = 564 \angle -45^\circ \text{ Amps}$$

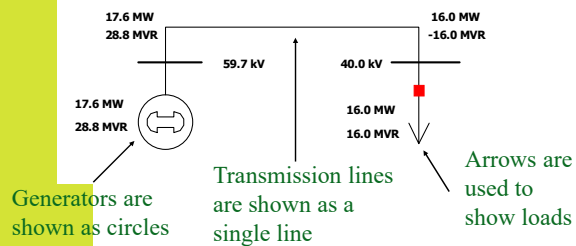
$$V = 59.7 \angle 13.6^\circ \text{ kV}$$

$$S = 33.7 \angle 58.6^\circ \text{ MVA} = 17.6 + j28.8 \text{ MVA}$$

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## POWER SYSTEM NOTATION

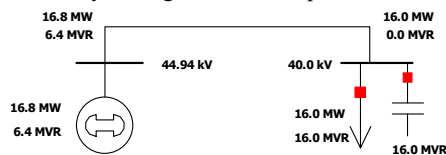
Power system components are usually shown as "one-line diagrams." Previous circuit redrawn



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## REACTIVE COMPENSATION

Key idea of reactive compensation is to supply reactive power locally. In the previous example this can be done by adding a 16 Mvar capacitor at the load.



Compensated circuit is identical to the first example with just real power load.

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## REACTIVE COMPENSATION, CONT'D

- Reactive compensation decreased the line flow from 564 Amps to 400 Amps. Advantages:
  - Lines losses, which are equal to  $I^2 R$  decrease
  - Lower current allows utility to use small wires, or alternatively, supply more load over the same wires
  - Voltage drop on the line is less
- Reactive compensation is used extensively by utilities
- Capacitors can be used to “correct” a load’s power factor to an arbitrary value.

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## POWER FACTOR CORRECTION EXAMPLE

Assume we have 100 kVA load with  $pf=0.8$  lagging, and would like to correct the  $pf$  to 0.95 lagging

$$S = 80 + j60 \text{ kVA} \quad \phi = \cos^{-1} 0.8 = 36.9^\circ$$

$$pf \text{ of } 0.95 \text{ requires } \phi_{\text{desired}} = \cos^{-1} 0.95 = 18.2^\circ$$

$$S_{\text{new}} = 80 + j(60 - Q_{\text{cap}})$$

$$\frac{60 - Q_{\text{cap}}}{80} = \tan 18.2^\circ \Rightarrow 60 - Q_{\text{cap}} = 26.3 \text{ kvar}$$

$$Q_{\text{cap}} = 33.7 \text{ kvar}$$

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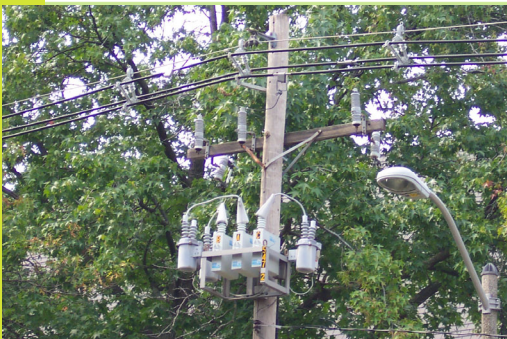
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## DISTRIBUTION SYSTEM CAPACITORS



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